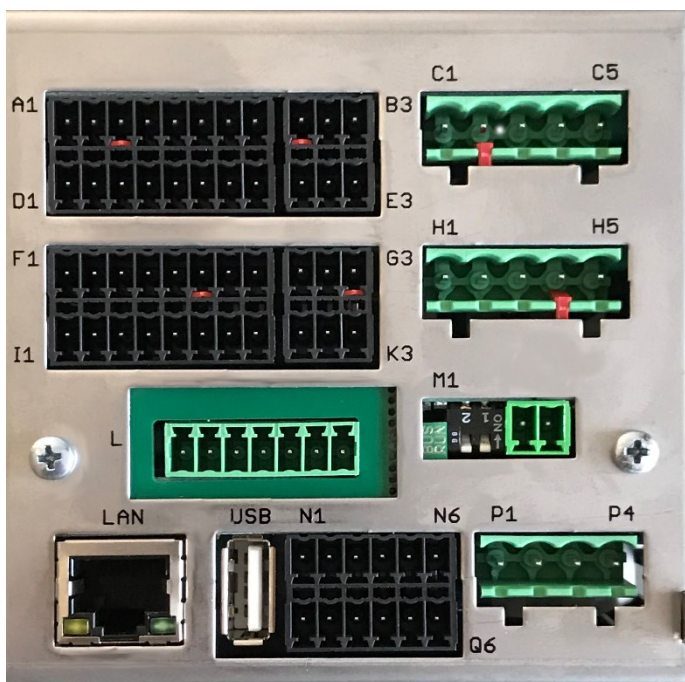




## R4020

### DIN Rail Temperature Controller With 1, 2, 4, 6, 8, 12\* or 16\* zones Heating/Cooling

\* With the extension module R4010 up to 16 zones can be connected.



Depth: 120mm  
Format: 116mm x 93mm

### DESCRIPTION AND OPERATING MANUAL

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# 1 General Information

Symbols used:

<b>www.elotech.de</b>	Messages shown by the controller are written in this font.
<b>MRS / MRE</b>	<b>Measuring Range Start / Measuring Range End</b>
<b>&lt;§&gt;</b>	Symbolizes the factory adjustment of the respective parameters.

## 2 Installation Instructions

Make sure the device is used for the intended purpose only.

R4020 controllers are designed for installation in control panels.  
Protect the device against impermissible humidity and contamination.

The permitted ambient temperature range may not be exceeded.  
Electrical connections must be made according to valid regulations and by properly qualified personnel.

If using thermocouple sensors, compensation lines have to be connected directly to the controller terminals. Sensors may be connected only in compliance with the programmed range.

Sensor cables and signal lines (e.g. logic or linear voltage outputs) must be laid separately from control lines and mains voltage supply cables (power cables).

In order to maintain CE-Compliance screened detectors - and signal lines have to be used. It is not permitted to connect the grounds of the sensor-inputs and logic-outputs with each other.

Separate installation of controller and inductive loads is recommended.  
Interference from contactor coils must be suppressed by connecting adapted RC-combinations parallel to the coils.  
Control circuits (e.g. for contactors) should not be connected to the mains power supply terminals of the controller.

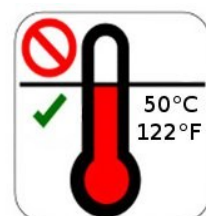
**The configuration parameters are generally to be selected first.**

### Disclaimer of Liability

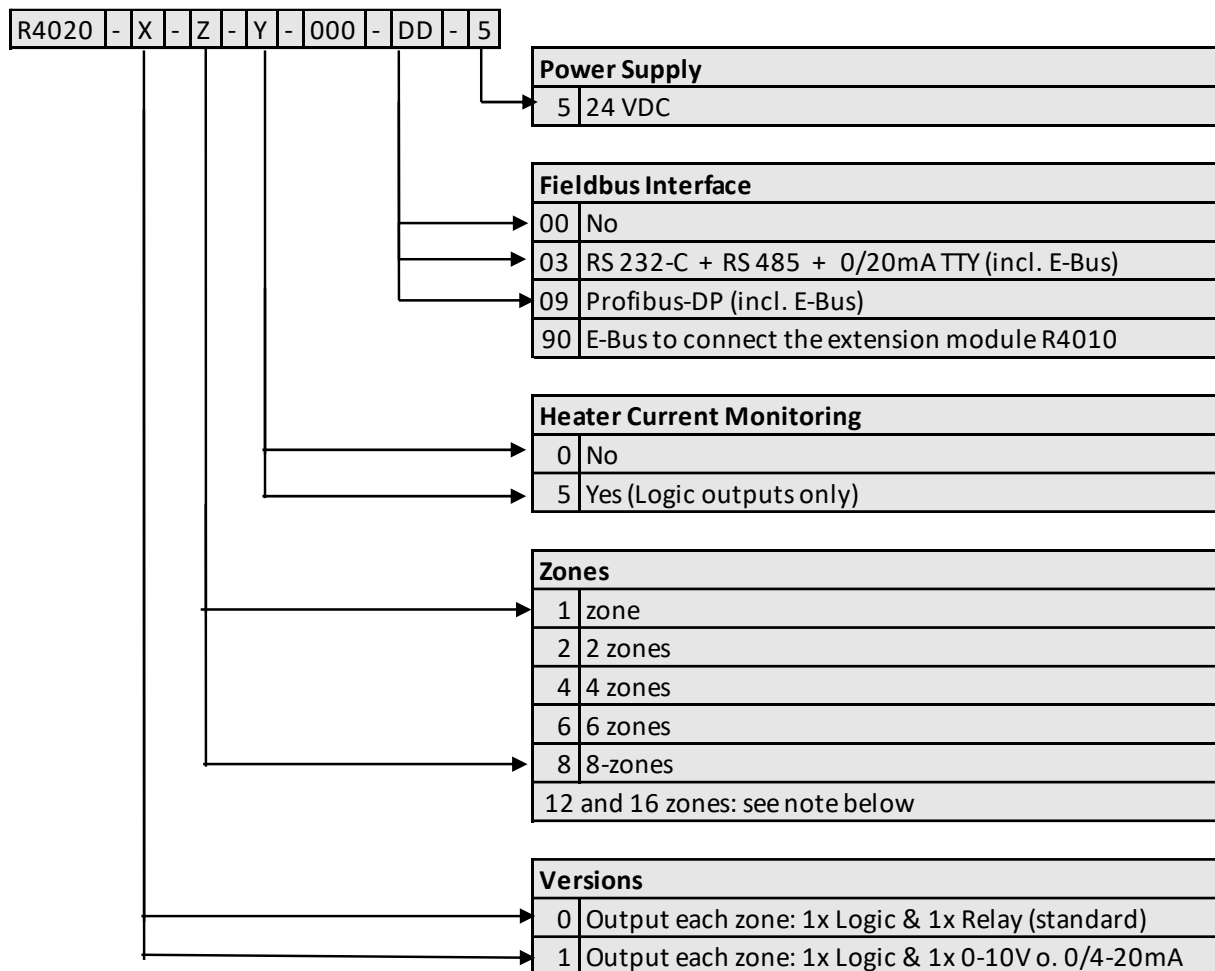
The contents of this document is checked for the conformity with the hardware and software described. Nevertheless, we are unable to preclude the possibility of deviations so that we are unable to assume warranty for full compliance. However, the information given in the publication is reviewed regularly. Necessary amendments are incorporated in the following editions.

We would be pleased to receive any improvement proposals which you may have.  
The information contained herein is subject to change without notice.

Electronic scrap and components are subject to special treatment and must be disposed of by authorised companies.



### 3 Type Code



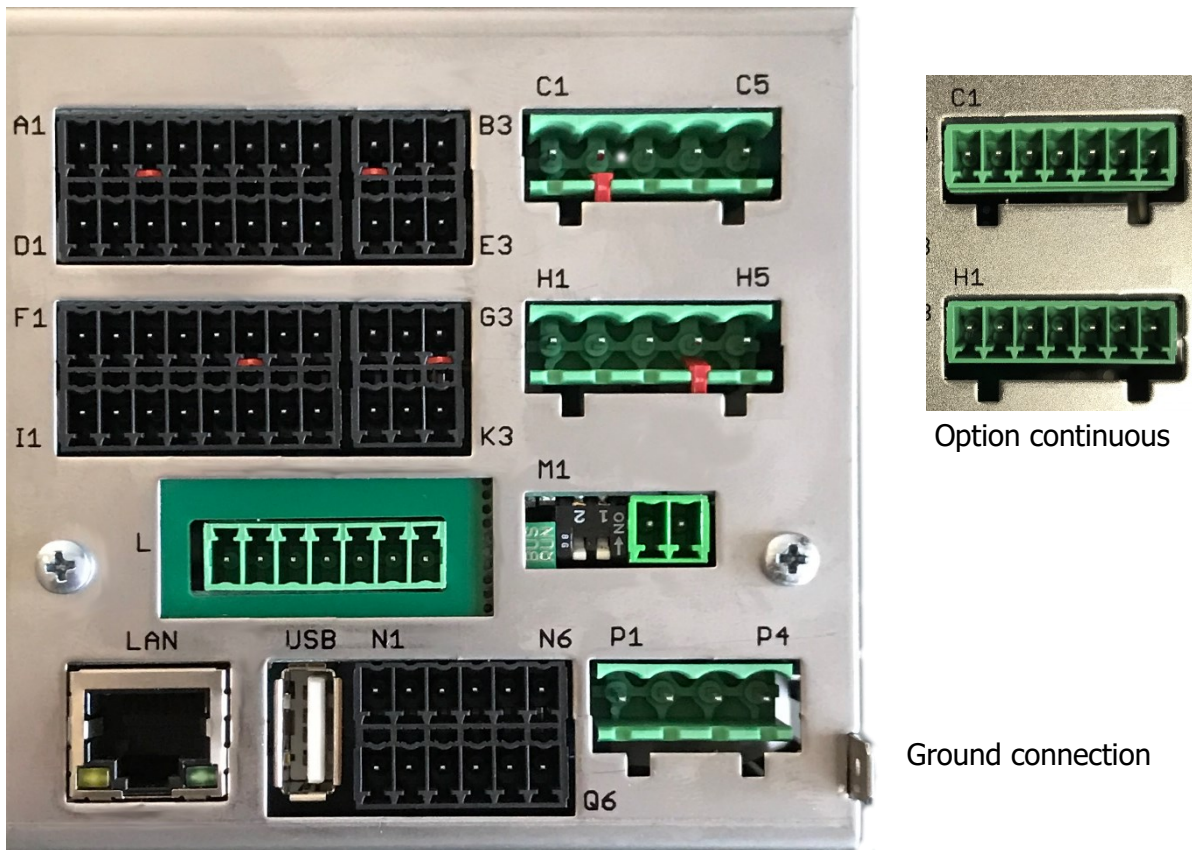
**DD** If 12 or 16 zones are required, an 8-zone controller and an expansion module R4010 (4 or 8 zones) must be ordered.

The E-bus on the R4020 is required for communication with the R4010.

If the required controller already has a fieldbus interface, then the E-bus interface is already available.

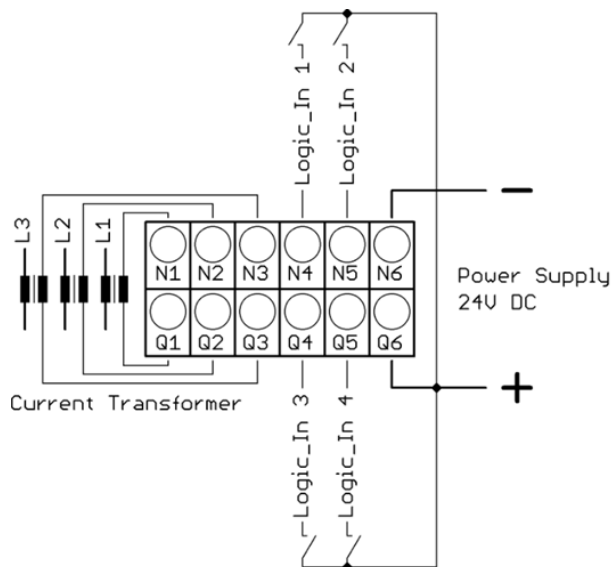
If no fieldbus interface is required, key 90 (E-bus) must be selected for the fieldbus.

## 4 Connection Diagram



The Ground connection (flat plug 6,3mm) must be connected to an earth rail via a thick cable ( $\geq 4\text{mm}^2$ ) in the shortest possible way ( $< 20\text{cm}$ )!

### 4.1 Connection Diagram: Power supply, Logic Inputs and Heater Current



#### Function of logic inputs

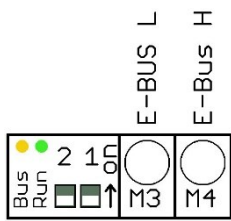
*In_1:	0 =	(*) Setpoint 1 active for all zones.
	1 =	(*) Setpoint 2 active for all zones
*In_1:	0 =	Stop program controller
	1 =	Start program controller
		*Depending on config. Logic input 1 $\rightarrow$ 7.2.3

In_2:	No function
-------	-------------

In_3:	No function
-------	-------------

In_4:	No function
-------	-------------

## 4.2 Connection diagram LEDs, DIP-Switches and E-Bus



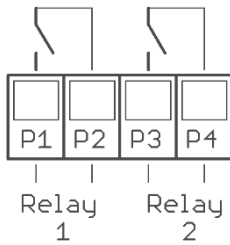
The LEDs are used to show operating states. E.g. LED Run is glowing green for normal operation. Functions can be controlled with the dip switches. Such as resetting the IP address and initiating the firmware update.

The extension module R4010, for extension to 12 or 16 zones, is connected to the R4020 via the E-bus.

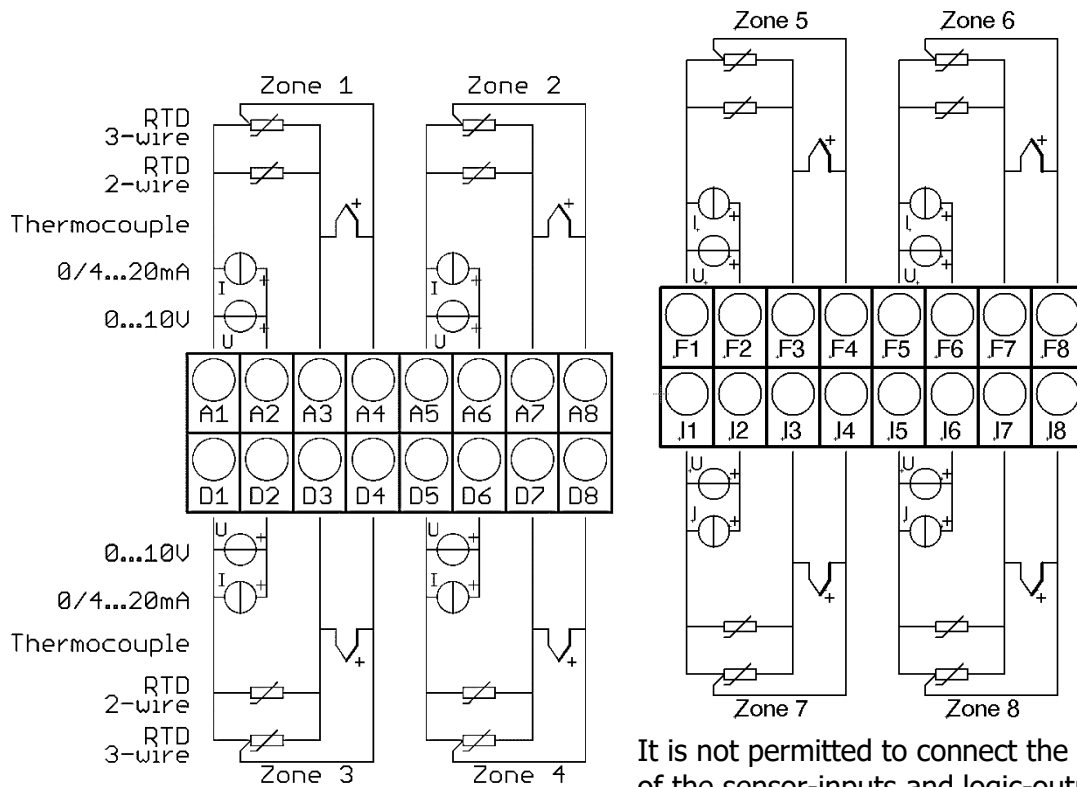
The lines „E-Bus L“ and E-Bus H“ must be connected to the corresponding terminals of the R4010.

The connection must be designed as a shielded cable. The shield has to be connected the earth (housing) at the R4010 side.

## 4.3 Connection Diagram: Monitoring Relay



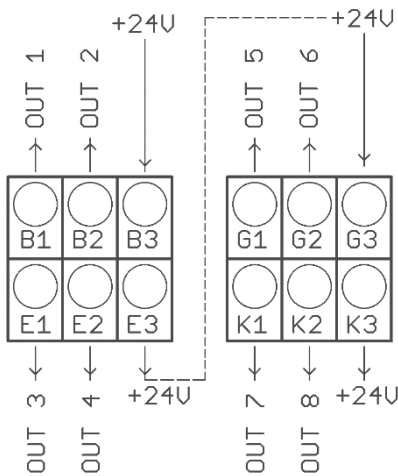
## 4.4 Connection Diagram: Sensor Inputs



It is not permitted to connect the grounds of the sensor-inputs and logic-outputs with each other!

RTD/Ni120: The parameter "Sensor Settings / Sensor" has to be set accordingly to the connection diagram (2-wire/3-wire)

### 4.5 Connection Diagram: Logic Outputs

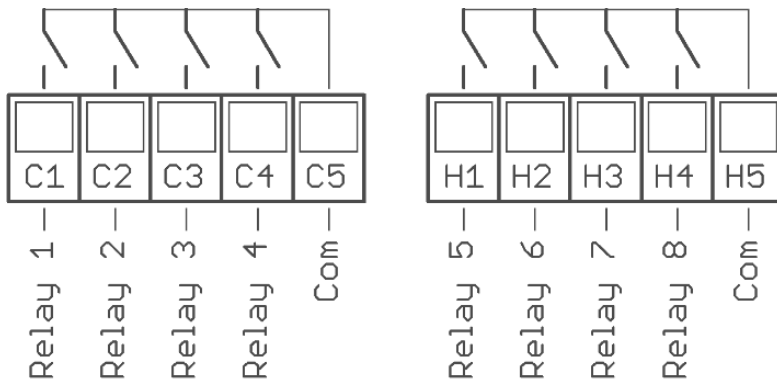


The power supply for the logic outputs has to be wired externally:  
+24V must be applied to the terminals B3 and G3.

B3 is connected internally to E3 and G3 is connected to K3. So the terminals E3 and K3 can be used to loop the +24V.

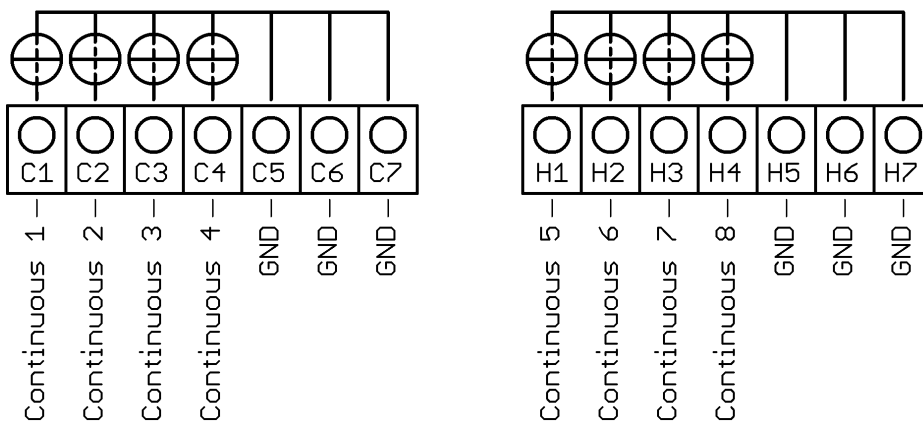
The 24V are switched to the outputs out x and thus control the SSRs. Reference potential is the ground of the supply voltage.

### 4.6 Connection Diagram: Relay Outputs



### 4.7 Connection diagram Continuous outputs (option)

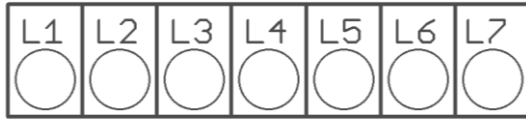
If continuous outputs are existed, the relay outputs are not available.



The GND connection terminals C5 - C7 and H5 - H7 are bridged. The output automatically switches to current or voltage, depending on the connected load.

## 4.8 Connection Diagram: Fieldbus Interfaces

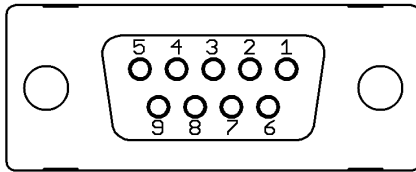
### Type 03 / 07 : Serial Interface / CAN



							Bus	Type	Remark
	A	B					RS485	03	Parameter HW-config = RS232 / RS485
			RxD	TxD	GND		RS232	03	Parameter HW-config = RS232 / RS485
					-	+	TTY	03	Parameter HW-config = TTY (current loop)
	H	L					CAN	07	Not available at the moment

The serial fieldbus module (Type: 03) contains the three interfaces RS232, RS485 und TTY. By choosing the connection and setting the parameter "HW-config" the desired bus is selected.

### Typ 09: Profibus



Pin 3	Data RxD / TxD - P
Pin 5	GND
Pin 6	+5V
Pin 8	Data RxD / TxD - N

The 5V-Supply is designed for the supply of the termination resistors. Further loads are not allowed.

## 4.9 Connection Diagram: LAN and USB

USB: Make a firmware update. (Please use FAT formatted USB flash drives.)

LAN: Connection to configuration tool **EloVision 3**.

Read and write parameters by MODBUS-TCP protocol.



## 5 Establishing a Modbus-TCP connection

### 5.1 Changing the IP address for the LAN interface

Normally, the address 192.168.100.100 will not correspond to the network in which the controller is to be used.

To change the address, the controller must be connected to a PC via its delivery address. For example, a Windows laptop with an Ethernet interface can be used for this.

1. Connect the R4020 controller directly to the PC using a LAN cable. (or via a switch).
2. Set a fixed network address on the PC for the network port used.

Windows 10: Open 'System' **settings**. Select **Network and Internet**. Click on the **Ethernet** line. Select the connector you are using. Then click the Edit button in the **IP Settings** section. See image. Make the following settings:

Setting: Manual

IPv4: On

IP address 192.168.100.101

Subnet length: 24 bits

*Alternative subnet mask: 255.255.255.0*

Gateway: 192.168.100.1

IPv6: Off

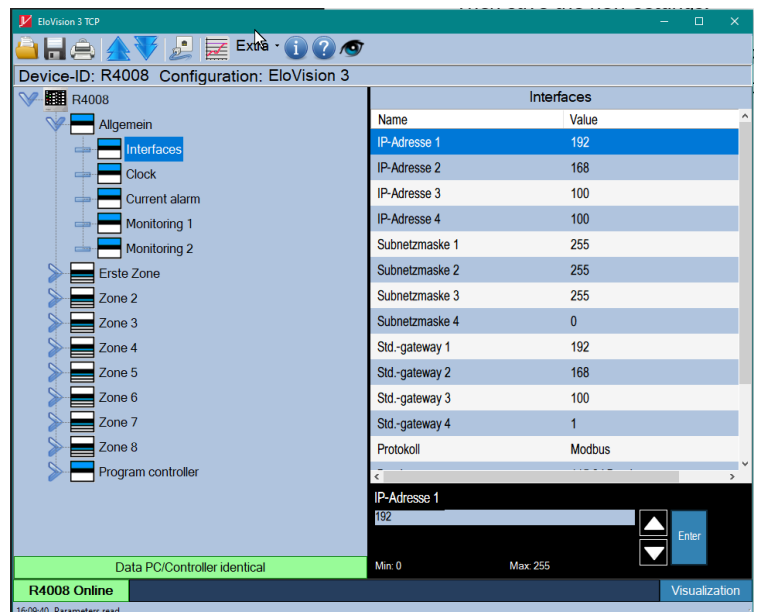
Then save the new settings.

3. With the help of EloVision 3 or another Modbus-TCP tool, the controller can now be accessed, and a suitable IP configuration can be made.
4. Please set the pre-set controller address 192.168.100.100 in EloVision 3. Please refer to the EloVision 3 operating instructions.

The screenshot shows the 'IP-Einstellungen bearbeiten' (Edit IP settings) window in Windows 10. The 'Manuell' (Manual) option is selected. Under 'IPv4', the 'Ein' (On) toggle is active. The 'IP-Adresse' (IP address) field is set to 192.168.100.101, the 'Subnetzpräfixlänge' (Subnet prefix length) is 24, and the 'Gateway' is 192.168.100.1. There are empty fields for 'Bevorzugter DNS' (Preferred DNS) and 'Alternativer DNS' (Alternate DNS). Under 'IPv6', the 'Aus' (Off) toggle is active. At the bottom, there are 'Speichern' (Save) and 'Abbrechen' (Cancel) buttons.

In menu General/Interfaces, the parameters can be changed in EloVision. They only become active after the controller has been restarted or after DIP switch 1 has been switched off.

If the address of the controller has already been set to an unknown address, the IP address can be set to factory setting via DIP switch 1. See 7.3.4 Switching the IP address to the factory default setting.



## 5.2 Running the controller via the Modbus TCP interface

With the network configuration correctly set, the controller can run in the intended target network.

## 6 Zone extension (R4010) configuration

The R4020 can be extended with a R4010 to up to 8 zones. Configuration and connection of a R4010 are shown in a separate manual.

To activate the additional zones in the R4020 the parameter *Zone extension* must be switched on. The parameter is in the menu *Common*.

The parameter *Zone extension* has to be set (depending on the number of zones of the R4010) to the number of zones of the whole system.

After setting the zone extension the R4020 must be rebooted.

Device-ID: R4008 Configuration: EloVision 3

R4008

- Common
- Zone 1
- Zone 2
- Zone 3
- Zone 4
- Zone 5
- Zone 6
- Zone 7
- Zone 8
- Program controller

Name	Value
Language	English (English)
Firmware	35,23
Zone offset	off
Heat up type	off
Authorisation (LOC)	All parameters adjustable
Sample rate	10 s Total: 33 Min.
Restart lock-out	off
Wizard at startup	off
<b>Zone extension</b>	<b>off</b>

**Zone extension**

off  
12  
**16**

Data PC/Controller identical

R4008 Online Visualization

12:54:17 Parameters read

## 7 Parameters

The **Modbus** parameter codes are located below the parameter name. For example, 0x2000 for setpoint act..

Zone parameters end with 0x ## 00. The zone is selected with the low byte. Here zone 1 = 00; Zone 2 = 01. Please also read the associated Modbus description.

### 7.1 Zone – Parameter list

<b>Setpoint act.</b> 0x2000	<b>Setpoint min ... Setpoint max.</b>	Current setpoint used for control. Read only parameter
<b>Act. value</b> 0x1000		Actual temperature value RO-Parameter
<b>Current act. Value</b> 0x1100		Actual heating current value RO-Parameter
<b>Output ratio</b> 0x6000	<b>0 ... 100%</b>	Current output level RO-Parameter

<b>Conf. Indica- tor/Contr.</b> 0x8C00	<b>Off (0)</b>	Measuring- or controlling zone switched off
	<b>Controller (1)</b>	Controlling zone active <§>
	<b>Indicator (2)</b>	Measuring zone active

<b>Config. Setpoint/ Cascade</b> 0x2700	<b>Internal (0)</b>	The setpoint is generated from the setpoint 1 or setpoint 2 parameter. <§>
	<b>External setpoint (1)</b>	The setpoint is generated from the measured value of the zone set in the "Source zone ext. setpoint" parameter.
	<b>Cascade control- ler (2)</b>	This zone is the slave controller of the master controller set via the "Master zone cascade contr." parameter. The Start and End setpoint normalization parameters must be set in the Cascade scaling menu.

#### *Only with external setpoint configuration*

<b>Source zone ext. setpoint</b> 0x7400	The zone for generating the external setpoint is selected here. <ul style="list-style-type: none"> <li>➔ Only zones that do not use an ext. setpoint themselves can be selected.</li> <li>➔ If necessary, zones that are not designed as control zones can also be selected to generate the ext. setpoint. For example, with a 2-zone controller, zone 3 or 4 can also be used as external setpoint sources.</li> </ul>
--	--

#### *Only with cascade controller configuration*

<b>Master zone cas- cade contr.</b> 0x7500	Selection of the control zone for the master controller. This is connected to the current zone via the cascade control. The current zone is switched as the slave controller.
<b>Start setpoint- scaling</b> 0x2800	Setpoint temperature value of the slave zone with an actuating output value of the master zone of 0%
	Setting range: <b>MBA ... 0<sup>(*)</sup> ... MBE °C</b>
<b>End setpoint- scaling</b> 0x2900	Setpoint temperature value of the slave zone with a control output value of the leading zone of 100%
	Setting range: <b>MBA ... 100<sup>(*)</sup> ... MBE °C</b>

<i>Only with internal setpoint configuration</i>		
<b>Setpoint 1</b> 0x2100	<b>Setpoint min ...</b> <b>Setpoint max</b>	Setpoint 1 <§> = 0
<b>Setpoint 2</b> 0x2200	<b>OFF(Setpoint min) ...</b> <b>Setpoint max</b>	Setpoint 2 <§> = OFF As soon as the logic input In_1 is on level 1, setpoint 2 will become active on all zones in which the adjusted value is unlike "Off".

<b>Configuration</b> <b>Heating-Cooling</b> 0x8000	<b>Heating (0)</b>	Two-point controller: "Heating" <§>
	<b>Cooling (1)</b>	Two-point controller: "Cooling"
	<b>Non-lin. Cooling (2)</b>	Two-point controller: "Cooling", with non-linear characteristic curve for evaporation cooling
	<b>Heating-Cooling (3)</b>	Three-point controller: "Heating-Off-Cooling"
	<b>Heating - non-lin. Cool. (4)</b>	Three-point controller: "Heating-Off-Cooling", with non-linear characteristic curve for eva. cooling

### **Hints for adjusting the control parameters:**

As standard the controller operates in PD/I control mode, i.e. controlling without deviation and with practically no overshoot during start-up.

The control action can be altered in its structure by adjusting the following parameters:

a. no control action (on-off)	Setting P = off Continuing with the parameter "switching difference"
b. P-action	Setting D and I = off
c. PD-action	Setting I = off
d. PI-action	Setting D = off
e. PD/I	Modified PID-mode (set: P,D,I)

<b>Autotune</b> 0x8800	<b>off (0)</b>	Switches off autotune <§>
	<b>On (1)</b>	Activates autotune
	<b>All zones (2)</b>	Starts self-optimization on all activated zones.
	<b>Automatically (3)</b>	After a power restart auto-tuning starts automatically. If necessary after the soft start.

The tuning algorithm determines the characteristic values within the controlled process and calculates the valid feedback parameters (P, D, I) and the cycle time. (= 0.3 x D) of a PD/I- controller for a wide section of the range.

The autotune mode works during start-up shortly before the setpoint is reached. If activated after the setpoint has already been reached, the temperature will first drop by approx. 7% of the measuring range.

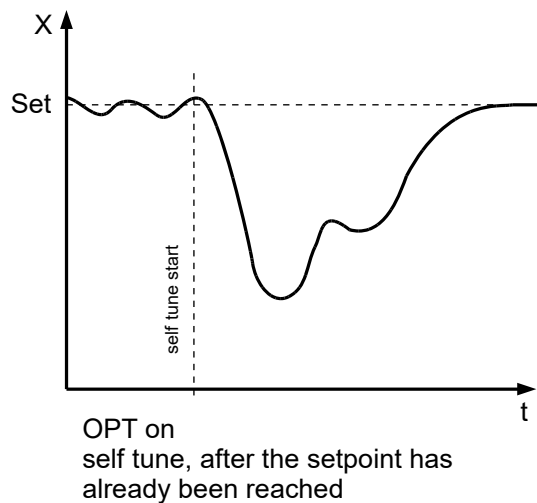
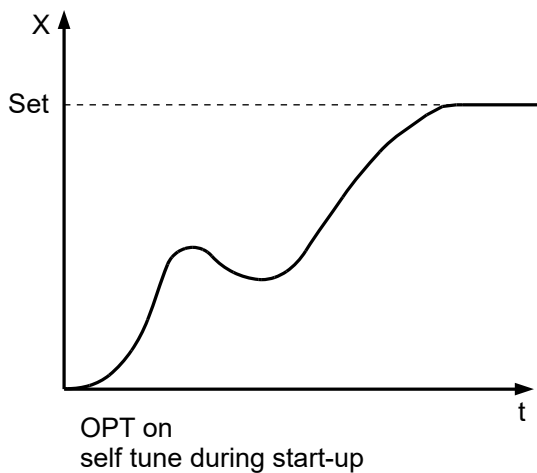
The tuning algorithm can be activated at any time by selecting the parameter **Autotune = "on"**. After having calculated the feedback parameters, the controller will lead the process value to the actual setpoint.

Selecting **Autotune = "off"** will stop the autotune function.

Autotune duration > 2 hours: autotune stops with an error message.

Conditions for starting the autotune algorithm:

- The setpoint must amount to at least 5% of the measurement range
- The sensor must not have a failure.
- The softstart function must not be active



Depending on the configuration, certain parameters are not visible.

<b>7.1.1 Heating Control Parameter</b>		
Only visible in operating modes heating or heating-cooling		
<b>P (Xp)</b> 0x4000	<b>OFF(0), 0.1 ... 400.0K</b>	Proportional range <b>&lt;§=10,0&gt;</b> Unit: Kelvin
<b>D (Tv)</b> 0x4100	<b>OFF(0), 1 ... 200s</b>	Derivative time <b>&lt;§=30s&gt;</b>
<b>I (Tn)</b> 0x4200	<b>OFF(0), 1 ... 1000s</b>	Reset time <b>&lt;§=150&gt;</b>
<b>Cycle-time</b> 0x4300	<b>0.5 ... 240.0s</b>	<b>&lt;§=10,0s&gt;</b> The switching frequency of the actuator can be determined through the cycle time. In this time interval the controller switches on and off once. <u>Voltage outputs for solid state relays (SSR):</u> Cycle time: 0,5...10 s Preferred settings for rapid control processes: 0,8s <u>Relay outputs:</u> Cycle time: > 10 s The cycle time should be adjusted to a time as long as possible in order to minimize wear of the relay contacts.
<b>Max. Output ratio</b> 0x6400	<b>0 .. 100%</b>	<b>&lt;§=100%&gt;</b> The limitation of the output ratio is only necessary, if the heating energy supply is grossly oversized compared to the power required. Normally it should be switched off (Setting: 100 %). The limitation becomes effective when the controllers calculated output ratio is greater than the maximum permissible (limited) ratio. <b>Warning!</b> The output ratio limiting does not work during autotune.
<b>Hysteresis</b> 0x4700	Only adjustable if "(xp)" = off (on-off action, without feedback)	
	<b>OFF(0), 0.1 ... 80.0</b>	For measuring range without decimal point <b>&lt;§=0.1&gt;</b>
	<b>OFF(0), 0.01 ... 8.00</b>	For measuring range with decimal point <b>&lt;§=0.01&gt;</b>
	<p>The diagram illustrates hysteresis. A horizontal axis is labeled 'process value' and a vertical axis is labeled 'setpoint'. A shaded rectangular region is centered on the setpoint line, extending from -5.0 to +5.0. Above this region, a horizontal double-headed arrow indicates a width of 10.0, labeled 'Hysteresis:'. The setpoint is marked with a vertical dashed line.</p>	

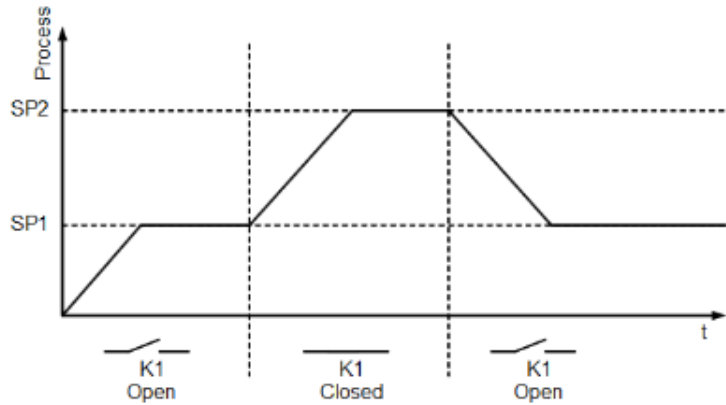
## 7.1.2 Cooling Control Parameter

Only visible in operating modes Cooling or Heating-Cooling

<b>P (Xp)</b> 0x5000	<b>OFF(0), 0.1 ... 400.0K</b>	Proportional band <b>&lt;ξ=10,0&gt;</b> Unit: Kelvin
<b>D (Tv)</b> 0x5100	<b>OFF(0), 1 ... 200s</b>	Rate time <b>&lt;ξ=30s&gt;</b>
<b>I (Tn)</b> 0x5200	<b>OFF(0), 1 ... 1000s</b>	Reset time <b>&lt;ξ=150&gt;</b>
<b>Cycle time</b> 0x5300	<b>0.5 ... 240.0s</b>	<p><b>&lt;ξ=10,0s&gt;</b> The switching frequency of the actuator can be determined by adjusting the cycle time. In this time interval the controller switches on and off once.</p> <p><u>Voltage outputs for solid state relays (SSR):</u> Cycle time: 0,5...10 s Optimal value for fast control loops: 0,8s</p> <p><u>Relay-Outputs:</u> Cycle time: &gt; 10 s In order to minimize the wear of the relay contacts the cycle time should be set as long as possible.</p>
<b>Max. Output ratio</b> 0x6900	<b>0 ... 100%</b>	<p><b>&lt;ξ=100%&gt;</b> Limitation of the output ratio is only necessary, if the power supply of the control route is grossly overdimensioned. Normally it should be switched off (Setting: 100 %). Output ratio limiting interferes, if the calculated output ratio of the controller is higher than the max. output ratio that was set.</p> <p><b>Caution!</b> Output ratio limiting does not work while auto-tune.</p>
<b>Hysteresis</b> 0x5700	Only adjustable if "P (xp)" = off (on-off action, without feedback)	
	<b>OFF(0), 0.1 ... 80.0</b>	For measuring range without decimal point <b>&lt;ξ=0.1&gt;</b>
	<b>OFF(0), 0.01 ... 8.00</b>	For measuring range with decimal point <b>&lt;ξ=0.01&gt;</b>
<b>Deadband</b> 0x4600	Switching point distance "heating" and "cooling" This parameter is available for "heating and cooling" operations only. (Configuration Heating-Cooling = Heating-Cooling)	
	<b>OFF(0), 0.1 ... 80.0</b>	For measuring range without decimal point <b>&lt;ξ=0.1&gt;</b>
	<b>OFF(0), 0.01 ... 8.00</b>	For measuring range with decimal point <b>&lt;ξ=0.01&gt;</b>

### 7.1.3 Ramps: Ramp rising / Ramp falling

A programmed ramp is always activated when the setpoint is changed or when the mains supply is switched on. The ramp starts at the actual process value and ends at the preselected setpoint. The ramp can be activated for both setpoint 1 and setpoint 2. By programming the second setpoint a setpoint profile can be obtained, accordingly (see example with external contact In\_1 (K1) below).



<b>Ramp rising</b> 0x2F00	<b>OFF(0), 0.1 ... 99,9</b>	°K/min for measurement range without decimal point <b>&lt;§=Off&gt;</b>
	<b>OFF(0), 0.01 ... 9.99</b>	°K/min for measurement range with decimal point
<b>Ramp falling</b> 0x2D00	<b>OFF(0), 0.1 ... 99,9</b>	°K/min for measurement range without decimal point <b>&lt;§=Off&gt;</b>
	<b>OFF(0), 0.01 ... 9.99</b>	°K/min for measurement range with decimal point



## 7.1.4 Softstart

## Softstart-Funktion

For using the softstart function, make sure that the instrument is programmed to voltage (logic) outputs. This function is not allowed for relay outputs. Otherwise the relays will be damaged. During the softstart the controller's heating output response is limited to a pre-selected ratio, in order to achieve a slow drying of high performance heat cartridges. This results in a slower, more regular heating period.

Simultaneously the output clock frequency is quadrupled.

Once the process value reaches the softstart setpoint, it remains stable at this value for the preselected duration time. At the end of this period the process value rises to the valid setpoint. If the softstart is active, the controller's autotune function cannot operate.

If a setpoint ramp has been programmed, the softstart has priority, and the ramp will become active after the softstart has been completed.

The softstart only works:

- if the parameter P (xp) is programmed > 0,1%
- if the actual process value is lower than the softstart setpoint – 5% of the selected measuring range

It is possible to select this function for each zone individually.

<b>Softstart On/Off</b> 0x6D00	<b>Off (0)</b>	Softstart function not active. <§> The remaining softstart parameters are not displayed.
	<b>On (1)</b>	Softstart function is active.
<b>Softstart Output ratio</b> 0x6A00	<b>10 ... 100%</b>	<b>&lt;§ = 30&gt;</b>
<b>Softstart Setpoint</b> 0x6B00	<b>Range: Setpoint min...setpoint max.</b>	<b>&lt;§ = 100°C&gt;</b>
<b>Duration time</b> 0x6C00	<b>Off(0), 0.1...10.0min</b>	<b>&lt;§ = 2.0 min&gt;</b>
<b>Output mode</b> 0x8B00	<b>Controller mode (0)</b>	Controller mode
	<b>Mode AUTOM. (1)</b>	In the event of sensor break the last valid output ratio is maintained.  Like the setpoint, the output ratio can be changed manually.  Under the following circumstances, the output ratio will be 0%:  - if the output ratio was at the time of sensor break 100% - if the controller is working along a setpoint-ramp - if the control deviation from the measuring range was at time of sensor break > 0,25% - if parameter is set P (xp) = 0 - if softstart was active at the time of sensor break.

		A few seconds after sensor break has been rectified, the controller returns to automatic operation and calculates the required output ratio.
	<b>Mode MANUAL (2)</b>	The controller now operates as an actuator only. The control function is inactive  Process display: Actual process value. Setpoint display: Display of current output ratio in %. The output ratio can be changed manually.
<b>Manual output ratio</b> 0x6200	<b>0 ... 100 %</b>	Only effective if the controller is in "Manual" mode.

7.1.5 Sensor settings		All parameters for sensor configuration
Sensor 0x1A00	Linear 0...10 V (0)	Voltage 0 to 10 V
	Linear 0...20 mA (1)	Current 0...20mA
	Linear 4...20 mA (2)	Current Live Zero 4...20mA
	PT100 2-wire (3)	Pt 100 (RTD) 2-wire connection -100...800°C
	PT100 3-wire (4)	Pt 100 (RTD) 3-wire connection -100...800°C
	Ni120 2-wire (5)	Nickel 120 2-wire connection 0...250°C
	Ni120 3-wire (6)	Nickel 120 3-wire connection 0...250°C
	(TC) Fe-CuNi (J) (7)	Thermocouple Type J 0...800°C
	(TC) NiCr-Ni (K) (8)	Thermocouple Type K 0...1200°C
	(TC) Fe-CuNi (L) (9)	Thermocouple Type L 0...800°C
	NiCrSi-NiSi (N) (10)	Thermocouple Type N 0...1200°C
(TC) PtRh-Pt (S) (11)	Thermocouple Type S 0...1600°C	
Please NOTE : If the sensor selection is changed and the value is out of the new measuring range, the following parameters will be reset.		
Setpoint 1, Setpoint 2: Setpoint limitation min. Setpoint min.: Measuring range bottom Setpoint max: Measuring range top Setpoint ramp rising/falling: off Limit values: off Actual process value offset: off Setpoint softstart: setpoint min. softstart: off		
Process offset 0x1800	-999..0..1000°C	<b>&lt;§= 0°C&gt;</b> This parameter serves to correct the input signal: - the correction of a gradient between the measuring point and the sensor tip - line resistance balancing at 2-wire-RTD - Correction of the control deviation when using P or PD action. If for example the offset value is set to +5°C, then the real temperature measured by the sensor is 5°C less than the displayed actual process value. Make sure that the adjusted actual temperature value should not fall below or exceed the measuring range limits.
Setpoint min. 0x2B00	MR-Start ... Setpoint max.	Lowest adjustable setpoint value. <b>&lt;§ = 0&gt;</b> MR-Start: Start of measurement range
Setpoint max. 0x2C00	Setpoint min ... MR-End	Highest adjustable setpoint value. <b>&lt;§= 400&gt;</b> MR-End: End of measurement range
The minimal span of linear value min. and max. is 100, the maximal span is 2000.		
Linear value min. For linear measurement range only 0x1E00	-900 ... (Linear value max. -100)	Measuring range starting value of the linear scale. <b>&lt;§= 0,0&gt;</b>

<b>Linear value max.</b> For linear measurement range only 0x1F00	<b>(Linear value min. +100) ... 10.000</b>	Measuring range final value of the linear scale. <b>&lt;§= 100,0&gt;</b>
<b>Decimal</b> For linear measurement range only 0x1D00	<b>0 ... 2</b>	Decimal of the linear measuring range. <b>&lt;§= 1&gt;</b>
<b>Unit zone</b> 0x7000	<b>°C(0) ... °F(1)</b>	For <b>control</b> zones, you can choose between ° C and ° F. <b>&lt;§=°C&gt;</b> The temperature values of the selected zone are set to the specified unit with this parameter. Please check all temperature values after adjustment. (Limit values, setpoints, setpoint limits, actual value offset and, if applicable, the linear limits.)

## 7.1.6 Control outputs

Possible settings for the logic outputs and relay or continuous outputs.  
This is used to determine which signal is sent to the output.

<b>Conf. digital out</b> 0x8100	<b>Off (0)</b>	No function
	<b>Heating (1)</b>	Output of the heating signal at digital output x. <§>
	<b>Cooling (2)</b>	Output of the cooling signal at digital output x.
	<b>Limit 1 (3)</b>	Output of limit violation 1 to digital output x.
	<b>Limit 2 (4)</b>	Output of limit violation 2 to digital output x.

When using the relay as the actuating output, the switching cycle time must be set as long as possible in order to minimize the contact wear of the relay.

<b>Conf. relay out</b> 0x8200	<b>Off (0)</b>	No function
	<b>Heating (1)</b>	Output of the heating signal at relay x. <§>
	<b>Cooling (2)</b>	Output of the cooling signal at relay x.
	<b>Limit 1 (3)</b>	Output of limit violation 1 to relay x.
	<b>Limit 2 (4)</b>	Output of limit violation 2 to relay x.

<b>Continuous out configuration (Option)</b> 0x8300	<b>Off (0)</b>	No function
	<b>Heating (1) output ratio</b>	Output of the heating output ratio at continuous output x <§> (0..20mA or 0..10V)
	<b>Cooling (2) Output ratio</b>	Output of the cooling output ratio at continuous output x (0..20mA or 0..10V)
	<b>Current value (3)</b>	Output of the current value to the continuous output x (0..20mA or 0..10V)
	<b>Heating out-put ratio live zero (4)</b>	Output of the heating output ratio at continuous output x with offset zero. (4..20mA or 2..10V)
	<b>Cooling out-put ratio live zero (5)</b>	Output of the heating output ratio at continuous output x with offset zero. (4..20mA or 2..10V)
	<b>Current value live zero (6)</b>	Output of the current value to the continuous output x with offset zero. (4..20mA or 2..10V)

The minimal span of Continuous out min. and max. is 10.

<b>Cont. out min.</b> 0x8600 For "continuous out configuration" = "Current value" only	<b>MR-Start ... (Cont. out max. -10)</b>	Starting value of the linear output. <§= 0> Corresponds to 0/4mA or 0/2V.
--	--	--

<b>Cont. out max.</b> 0x8700 For "continuous out configuration" = "Current value" only	<b>(Cont. out min. +10) ... MR-End</b>	Final value of the linear output. <§= 800> Corresponds to 20mA or 10V.
--	--	---

## 7.1.7 Configuration Limit 1+2

Settings for limit values min./max. and configuration of limit monitoring 1/2		
<p>The controller features two independent limit monitors. The limit value monitoring can be configured zone by zone.</p> <p>These limit values can be output to the monitoring relays via the monitoring function (0). Irrespective of this, the limit value overruns can be output on the zone relays or logic outputs.</p> <p>With a programmed setpoint ramp, the relative limit values are tracked to the current ramp setpoints. In the case of sensor and line errors, the limit value violations react in the same way as range override.</p>		
Desired function	Setpoint based limit alarm	Absolute limit alarm
<p>Limit exceeded.</p> <p>The actual value must be greater than the sum of the max. and setpoint or as the absolute limit for the limit monitor to become active.</p>		
<p>Falling below the limit.</p> <p>The actual value must be smaller than the difference of (setpoint – limit min.) or smaller than the absolute limit min., so that the limit value monitoring becomes active.</p>		
<p>Double-sided limit monitoring.</p> <p>The actual value must be outside the range for the limit value monitoring to become active.</p>		
<p><b>Limit values</b> 0x3600/0x3700</p> <p><b>Limit value 1 / 2 (min.)</b></p>	<p>Relative to setpoint: -200...0;OFF (+1 <math>\triangleq</math> OFF&lt;§&gt;)</p> <p>Absolute: MB-Start&lt;§&gt; ... MB-End</p>	
<p>0x3800/0x3900</p> <p><b>Limit value 1 / 2 (max.)</b></p>	<p>Relative to setpoint: OFF;0...200 (-1 <math>\triangleq</math> OFF&lt;§&gt;)</p> <p>Absolute: MB-Start&lt;§&gt; ... MB-End</p>	
<p><b>Type limit</b> 0x3400 0x3500</p>	<p><b>Absolute (0)</b></p> <p><b>Based on setpoint (1)</b></p>	<p>Absolute limits. Not dependent on setpoint. &lt;§&gt;</p> <p>Limits relative to setpoint.</p>
<p><b>Delay</b> 0xB900 0xBA00</p>	<p><b>OFF (0)</b></p> <p><b>1 ... 8000 s</b></p>	<p>⚡ -Alarm delay switched off. &lt;§&gt;</p> <p>⚡ -Alarm is delayed by selected time.</p>
<p><b>Self-retaining</b> 0xB700 0xB800</p>	<p><b>Off (0)</b></p> <p><b>On (1)</b></p>	<p>No self-holding of the temperature alarm. &lt;§&gt;</p> <p>An activation of the ⚡ -alarm will be stored. The ⚡ -alarm can be acknowledged in the window "Monitoring".</p>

<b>Start suppression</b> 0xB300 0xB400	<b>OFF (0)</b> <b>Without start up</b>	Start-up ⚠ -alarm suppression switched off <§>
	<b>Start up (1)</b> <b>Suppression Active</b>	Start-up ⚠ -alarm suppression active: Temperature must be within the limits once. Only then the ⚠ -alarm is activated when reaching the alarm value.
<b>Display colour</b> 0xB500 0xB600	<b>Red (0)</b>	The monitoring displays the ⚠ -alarm in red colour. <§>
	<b>Green (1)</b>	Intended for enabling signals: Display colour is green.
	<b>Orange (2)</b>	
<b>Switching Behaviour</b> 0xBB00 0xBC00	<b>Direct (0)</b>	The monitoring output is activated when the max. limit value has been exceeded or if the min. limit value has been undercut.
	<b>Inverse (1)</b>	The signal is inverted and output to the monitoring. If the min. limit value has been exceeded or if the max. limit value has been undercut the output is set.

## 7.1.8 Configuration Current alarm (option)

The heater current monitoring function is valid for all connected zones.  
 Only zones with logic output for the heating signal will take part in current monitoring.  
 Ensure that the limit value is set correctly to avoid false alarms in case of supply voltage changes. The alarm can be delayed by selecting a delay time to avoid false alarms caused by single disturbances.  
 The heater current measuring is designed for a current transformer 1:1000.  
 (Accessory type: M2000 1:1000 max. 60A)  
 When using other transformers the ratio can be modified.

<b>Current alarm limits / Undercurrent alarm value</b> 0x3A00	<b>OFF(0), 0.1 ... 99.9 A</b>	Zone parameter: Absolute value <b>&lt;§=OFF&gt;</b> Currents below this value will cause an alarm.
<b>Current alarm limits / Overcurrent alarm value</b> 0x3F00	<b>OFF(0), 0.1 ... 99.9 A</b>	Zone parameter: Absolute value <b>&lt;§=OFF&gt;</b> Currents above this value will cause an alarm.

## 7.2 Common Parameters

<b>Measure current</b> 0xCF53	<b>Off (0) / on (1)</b>	Enable or disable current measuring and monitoring.
<b>Leakage limit</b> 0xCF09  Monitoring an impermissible continuous current	<b>Limit value: OFF, 0,0...99,9 A &lt;§&gt;=0,3A</b>	SSRs (especially if they are combined with RC-combinations) normally have small leakage currents. These currents add up and the sum can lead to a permanent leakage current. A leakage current limit value is programmable. All values below this limit will not be considered in the alarm monitoring. The field "act. Leakage current" displays the leakage current that has just been measured. If a permanent current (SSR short circuit) is detected the alarm will be activated.  The zone with a permanent current can be detected by observing the actual process values (proves value too high).
<b>act. Leakage curr.</b> 0xCF0A		Display of the actual leakage current
<b>Current transformer</b> Turns ratio 0xCF16	<b>1:100 ... 1:9999</b>	<b>&lt;§ = 1:1000 for M2000&gt;</b>
<b>Cycle time</b> 0xCF08	<b>1...60s</b>	Time interval between the current measurements of two successive zones. <b>&lt;§ = 2s&gt;</b>
<b>Delay</b> 0xCF2F		Settings in 5 steps, unit: seconds The values depend on the cycle time and the number of active controller zones. <b>Off(0)</b> = no delay time active <b>&lt;§=off&gt;</b>



## 7.2.1 Configuration Monitoring 1+2

Settings for messages of monitoring 1. The same applies to monitoring (2).		
The controller has two independent monitoring relays. With the help of the monitoring several events of the controller can be routed (wired OR) to the relays.		
<b>Limit 1</b> M1: 0xCF23 M2: 0xCF29	--- (0)	Not selected <§ for Monitoring2>
	<b>One zone (1)</b> => Message	Once Limit 1 is active in one zone, monitoring 1(2) is set. <§ for Monitoring1>
	<b>All zones (2)</b> => Message	Monitoring 1(2) is not set until Limit 1 is active in all zones.
<b>Limit 2</b> M1: 0xCF24 M2: 0xCF2A	--- (0)	Not selected <§ for Monitoring1>
	<b>One zone (1)</b> => Message	Once Limit 2 is active in one zone, monitoring 1(2) is set. <§ for Monitoring2>
	<b>All zones (2)</b> => Message	Monitoring 1(2) is not set until Limit 2 is active in all zones.
<b>Sensor error</b> M1: 0xCF25 M2: 0xCF2B	--- (0)	Not selected <§ for Monitoring2>
	<b>Active (1)</b>	In the case of sensor break monitoring 1(2) is set. <§ for Monitoring1>
<b>Restart lock-out</b> M1: 0xCF26 M2: 0xCF2C	--- (0)	Not selected <§>
	<b>generate Signal (1)</b>	Monitoring 1(2) is set, if a restarting-incident triggered.
<b>System error</b> M1: 0xCF27 M2: 0xCF2D	--- (0)	Not selected <§>
	<b>Active (1)</b>	Monitoring 1(2) is set, if system error occurred.
<b>End of Program controller</b> M1: 0xCF31 M2: 0xCF32	--- (0)	Not selected <§>
	<b>generate Signal (1)</b>	Monitoring 1(2) is set, when the program controller has finished.
<b>Moni 1(2) Relay</b> M1: 0xCF03 M2: 0xCF05	<b>Direct (0)</b>	Relay switches on, if monitoring 1(2) is active. <§>
	<b>Indirect (1)</b>	Relay switches off, if monitoring 1(2) is active.
<b>Current alarm</b> 0xCF28 0xCF2E	--- (0)	Not selected <§ for Monitoring1>
	<b>Active (1)</b>	Monitoring 1(2) is set, if current alarm occurred. <§ for Monitoring2>

## 7.2.2 Field Bus / USB / LAN

<b>Menu: Fieldbus</b>		It depends on the installed field bus module what parameters will be visible.
<b>Protocol</b> 0xCF14	<b>Off (0)</b>	No protocol selected
	<b>Elotech (1)</b>	<SERIAL> ELOTECH-Standard-protocol <§>
	<b>Modbus (2)</b>	<SERIAL> Modbus-RTU-protocol
	<b>Arburg 1 (3)</b>	<SERIAL> Hot runner: One device address for all zones.
	<b>Arburg 2 (4)</b>	<SERIAL> Hot runner: Every zone has its own address.
	<b>Arburg 3 (5)</b>	<SERIAL> Protocol for temperature control systems
	<b>Profibus DP (6)</b>	<PROFIBUS> Profibus DP
<hr/>		
<b>Baudrate</b> <SERIAL> 0xCF12	<b>1.2 kBaud (0)</b>	1.200 Bit/s
	<b>2.4 kBaud (1)</b>	2.400 Bit/s
	<b>4.8 kBaud (2)</b>	4.800 Bit/s
	<b>9.6 kBaud (3)</b>	9.600 Bit/s <§>
	<b>19.2 kBaud (4)</b>	19.200 Bit/s
	<b>38.4 kBaud (5)</b>	38.400 Bit/s
<hr/>		
<b>Address</b> 0xCF11	<b>1 ... 255</b>	<b>1&lt;§&gt; ... 255</b> (ELOTECH-Standard) <b>1&lt;§&gt; ... 247</b> (Modbus-RTU-Protocol) <b>1&lt;§&gt; ... 32</b> (Arburg-Protocols) <b>2&lt;§&gt; ... 125</b> (Profibus) At this address a master communicates with the controller. Each controller needs a unique address.
	<hr/>	
<b>Format</b> 0xCF13	<b>7 E 1 (0)</b>	7 Data bits, 1 Stop bit, Parity Even <§>
	<b>7 O 1 (1)</b>	7 Data bits, 1 Stop bit, Parity Odd
	<b>7 E 2 (2)</b>	7 Data bits, 2 Stop bits, Parity Even
	<b>7 O 2 (3)</b>	7 Data bits, 2 Stop bits, Parity Odd
	<b>7 N 2 (4)</b>	7 Data bits, 2 Stop bits, Parity None
	<b>8 E 1 (5)</b>	8 Data bits, 1 Stop bit, Parity Even
	<b>8 O 1 (6)</b>	8 Data bits, 1 Stop bit, Parity Odd
	<b>8 N 1 (7)</b>	8 Data bits, 1 Stop bit, Parity None
<SERIAL>	<b>8 N 2 (8)</b>	8 Data bits, 2 Stop bits, Parity None
<hr/>		
<b>HW-config</b> 0xCF36	The serial fieldbus module has three integrated interfaces. Select here the desired interface:	
	<b>RS232/RS485 (0)</b>	Signals see connection diagram.
	<b>TTY (1)</b>	Signals see connection diagram.

<b>Menu: LAN</b>		Ethernet interface for connection to the configuration tool Elovision 3 or for a MODBUS-TCP communication.
<b>IP-address 1</b>	0xCF37	IP-Address <b>192</b> . 168 . 100 . 100 Part 1 <§>
<b>IP-address 2</b>	0xCF38	IP-Address 192 . <b>168</b> . 100 . 100 Part 2
<b>IP-address 3</b>	0xCF39	IP-Address 192 . 168 . <b>100</b> . 100 Part 3
<b>IP-address 4</b>	0xCF3A	IP-Address 192 . 168 . 100 . <b>100</b> Part 4
<b>Subnet mask</b>		
<b>Subnet mask 1</b>	0xCF3B	Subnet mask <b>255</b> . 255 . 255 . 0 Part 1 <§>
<b>Subnet mask 2</b>	0xCF3C	Subnet mask 255 . <b>255</b> . 255 . 0 Part 2 <§>
<b>Subnet mask 3</b>	0xCF3D	Subnet mask 255 . 255 . <b>255</b> . 0 Part 3 <§>
<b>Subnet mask 4</b>	0xCF3E	Subnet mask 255 . 255 . 255 . <b>0</b> Part 4 <§>
<b>Default gateway</b>		
<b>def.-gateway 1</b>	0xCF3F	Default gateway <b>192</b> . 168 . 100 . 1 Part 1 <§>
<b>def.-gateway 2</b>	0xCF40	Default gateway 192 . <b>168</b> . 100 . 1 Part 2 <§>
<b>def.-gateway 3</b>	0xCF41	Default gateway 192 . 168 . <b>100</b> . 1 Part 3 <§>
<b>def.-gateway 4</b>	0xCF42	Default gateway 192 . 168 . 100 . <b>1</b> Part 4 <§>

## 7.2.3 Settings

<b>Language</b> 0xCF0F	<b>Deutsch (German)</b>	German (0) <§>
	<b>English (English)</b>	English (1)
<b>Clock, Time, Date</b>		
<b>Time</b>	<b>Hours</b> 0xCF43	Number value 0 ... 23
	<b>Minutes</b> 0xCF44	Number value 0 ... 59
<b>Day / Month</b>	<b>Day</b> 0xCF45	Number value 1 ... 31
	<b>Month</b> 0xCF46	Number value 1 ... 12
<b>Year</b> 0xCF47	<b>2000 ... 2150</b>	Adjustment of calendar year
The function of the first logic input can be configured here.		
<b>Logic input 1 configuration</b> 0xCF50	<b>Setpoint 2: (0)</b>	Closing the logic input switches to setpoint 2 if setpoint 2 is not switched off for the respective zone.
	<b>Program controller: (1)</b>	Closing the logic input starts the program controller. Provided a program controller has been configured. Opening the contact stops the program controller.
<b>Start delay</b> 0xCF51	<b>off (*) (0)</b>	No delay in the output of the output level for heating or cooling after restart.
	<b>Time (1)</b>	The output level output is blocked for the <b>Delay time</b> set below.
	<b>Communication (2)</b>	The output level output is stopped until the first interface communication has taken place. (data exchange)
<b>Delay time</b> 0xCF52	<b>10s(*) ... 1000s</b>	Only visible if <b>Start delay</b> is set to <b>Time</b> . A time can be specified here. After the device is restarted, the output level is blocked for this time.
<b>Zone offset</b> 0xCF0C	<b>OFF (0)</b>	<§>
	<b>1 ... 91</b>	The adjusted offset value is added to the displayed zone numbers in the windows. Therefore a continuous numbering of the zones can be achieved if more than one device is used. Examples: Offset= OFF: Zone numbering: 1-8 Offset= 4: Zone numbering: 5-12
<b>Heat up type</b> 0xCF18	<b>Off (0)</b>	Compound and energy opt. heating switched off <§>
	<b>Even heat up (1)</b>	Compound heating is switched on. The switched-on zones are heated up in a network. This makes sense for controlled systems of different speeds, the temperatures of which should not differ greatly from one another. Faster zones are aimed at the slower zones.
	<b>Energy opt. (2) heat up</b>	This function has the aim of reducing the energy required by time-shifted switching of the control zones.

<b>Training</b> 0xCF4A	<b>off (0)</b>	Normal state. After switching on the function <b>Energy opt. heating</b> will be performed.
	<b>on (1)</b>	The next time the system is switched on, the heat up times of the individual zones are determined. After heating up, the parameter is automatically set to <b>off</b> .
<b>Participating zones</b> 0xCF4B	<b>zone 1=BIT_0</b> <b>zone 2=BIT_1</b> <b>etc.</b>	Selection of the zones that should take part in the respective type of heating. Factory setting: <b>All zones activated</b> (Bit parameters)
<b>Heat up times</b> 0xBD00	<b>0(*)... 30000 s</b>	Display of the zone-assigned times that were determined during the <b>training phase</b> . The values can also be entered manually.

### 7.3 Program control: Selection/Setting

<b>Program number</b> 0xC302	1 ... 8	Selection of the active Program.
<b>Program parameters</b>		
<b>Zone assignment</b>	0x000 ... 0xffff	Bit-by-bit specification of the zone that takes part in the program. From bit 0 (0x0001) for zone 1 to bit 15 (0x8000) for zone 16.
<b>Display Continue if</b>	<b>Time expired</b>	All steps are executed according to the predefined time grid.
	<b>Temp. reached</b>	After the ramp time has elapsed, the current step temperature is controlled until all the relevant zones have reached this setpoint. * The setpoint must be reached up to + - 2K.
<b>Program end</b>	<b>setpoint 1</b>	After completion of the last step, the control setpoint is further regulated. Normally setpoint 1.
	<b>Last setpoint</b>	After the last step has been completed, the temperature of the last step is further regulated.
	<b>Repeat</b>	After the last step has been completed, step 1 is started again.
<b>Number of steps</b>	1 ... 8	Count of steps.

#### Program step parameters

<b>Ramp duration</b>	0:00 ... 99:59h	Time setting in which the setpoint is to go up from the previous step temperature to the temperature of the current step. In the first step, the actual value is set as the start setpoint. * If no ramp is desired, set this time to 0: 00h.
<b>Temperature</b>	-100 ... 1600°C	Temperature for this step.
<b>Dwell time</b>	0:00 ... 99:59h	Time for the hold time of the current step temperature. The dwell time starts after the end of the ramp duration. When configuration is switched to "temp. reached", this time does not start until all the zones involved have the current step temperature. * Disabled zones are ignored. * For functional reasons, a "Dwell time" of at least one minute is used when the "Continue if" setting is set to "Temperature reached", even if the dwell time is set to "0:00h".

### 7.3.1 Procedure of the program control:

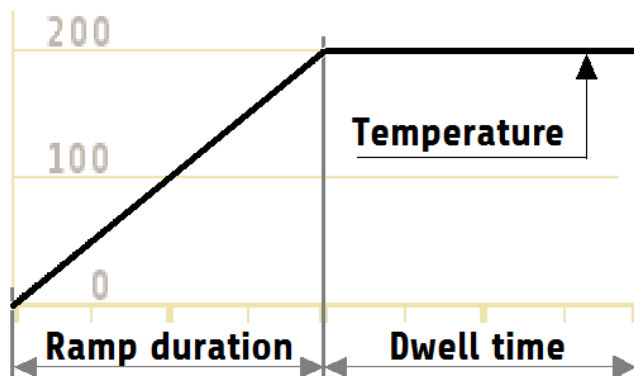
The first step is to determine whether the program controller should run after a fixed time grid, or whether the respective step temperature must first be reached in order to reach the respective holding phase. (See parameter "Continue if")

You should also consider how the program controller should control the temperature after the end of the program. Three options are available: Setpoint 1, Last setpoint and Repeat. For more details, see "Program End".

The number of steps [1 ... 8] must also be defined.

Now the time and temperature values for the desired steps must be entered in the "Setting the program steps" screen.

One step always involves ramp duration and dwell time. The ramp duration determines the time in which the setpoint is steadily increased from the previous temperature to the temperature of the current step. The dwell time is the duration of the current step temperature.



An exception is the ramp for the first step. Since the first step does not have a preliminary temperature, the ramp for all zones starts here with the current actual value of the first activated zone and ends at the temperature of step 1.

The ramp duration can be switched off by setting it to zero.

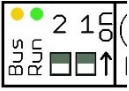
The dwell time is the duration of the current step temperature. If the parameter "Switch on" is set to "Temp. reached", the dwell time does not start until all zones have reached the step temperature.

After a network interruption with the program controller running, the program controller re-activates in the step at which the interruption took place.

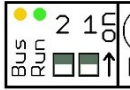




### 7.3.3 Firmware update

<b>Firmware version</b> 0xCF48	Displays the current firmware version.
<b>Firmware update</b>  	Start the firmware update by: <ol style="list-style-type: none"> <li>1. Switch off the supply voltage of the controller.</li> <li>2. Switch on both DIP switches.</li> <li>3. Insert the USB stick with the folder "EL4000.01_V20xx_xx.ELO" for the firmware update.</li> <li>4. Switch on the mains. LEDs yellow, green and red light up briefly.</li> <li>5. After approx. 2s the green LED flashes. Approx. 8s after mains on, the yellow and red LEDs light up. *Do not wait longer than approx. 22s. Then the green LED lights up. In this case, the unit must be switched off and on again to re-start the update process.</li> <li>6. While the red and yellow LEDs are lit, switch off both DIP switches. Now the yellow LED flashes for approx. 15s</li> <li>7. The green LED flashes for approx. 5 seconds.</li> <li>8. The firmware update has been successfully completed when the green LED lights up.</li> <li>9. Finally switch the unit off and on again.</li> </ol> <p>If the LED lights up red, repeat the procedure.</p>

### 7.3.4 Switching the IP address to the factory default setting

<b>Switching to the factory-set IP address</b>  	To switch the IP address to the factory default setting, please follow the steps below: <ol style="list-style-type: none"> <li>1. initial position: both dip switches are switched off. Green LED lights up.</li> <li>2. Switch on DIP switch 1. LED green flashes.              -&gt; IP address, standard gateway and subnet mask are set to factory default and are initialised.              IP address = 192.168.100.100              Subnet mask = 255.255.255.0              Default gateway = 192.168.100.1</li> <li>3. Now the controller can be accessed via this address, e.g. to set a new address for the controller. See also chapter 5.1 "Changing the IP address for the LAN interface".</li> <li>4. Switch off DIP switch 1. -&gt; The unit is initialised with the internal address.</li> </ol> <p>When DIP switch 1 is switched on, for example, a new address can be specified via EloVision, which is directly set and initialised when the DIP switch is switched off.</p>
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## 8 Error Messages

Error message	Cause	Possible remedy
ERR0	System error	Please send the controller back to the manufacturer.
ERR8	System error	Quit error message. Check the parameters. If the error is still there, send the controller back to the manufacturer.
ERR IO	Error I/O board See logbook: Error IO board 1 or 2  Error IO board 3 or 4	The connection to the input/output circuit board is broken. -> Internal card defective, please send the controller back to the manufacturer. -> If zone extension (0 menu About) is set to 12 or 16, the required additional module R4010 may not be connected. Switch off zone extension if necessary. <i>Info: All 4 sensors of the faulty card are set to sensor break.</i>

## 9 Technical Data

Input Pt100 (DIN)	2- or 3- wire connection possible Built-in protection against sensor breakage and short circuit Sensor current: ... < 1 mA Accuracy: ... < 0,2 % Linear error: ... < 0,2 % Influence of the ambient temperature: ... < 0,01 % / K
Input Thermocouple	Built-in internal compensation point and protection against sensor breakage and incorrect polarity. Accuracy: ... < 0,25 % Linear error: ... < 0,2 % Cold junction error: 0,5K Influence of the ambient temperature: ... < 0,01 % /
Input voltage 0...10V	Internal resistance > 100 k-Ohm Accuracy: < 0,25 % Linearity error: < 0,2 % Ambient temperature influence: < 0,01 % / K
Input current 0...20mA	Internal resistance < 100 Ohm Accuracy: < 0,25 % Linearity error: < 0,2 % Ambient temperature influence: < 0,01 % / K ! The input has high impedance when the controller is without supply voltage.
Logic input	Internal resistance > 22k-Ohm Level 0 < 2V Level 1 > 9V; max 30V
Heater current monitoring	Measuring input range: 0... 100mA corresponding 0,0...99,9A when using a current transformer 1: 1000. If the range is exceeded, the controller may be damaged.
Logic outputs	Bist. voltage, 0/24 V DC, max. 500 mA, short-circuit proof
Relay outputs/ Alarm outputs	Relay; max. 250V AC, max. 2A, resistive load
Continuous outputs	0...20 mA maximal load 300 Ohm; 0...10V minimal Load 5kOhm. Automatic switching, depending on connected load.
Fieldbus Interface:	Depends on the version of the device: - Serial: RS232, RS485, TTY (20mA) - Profibus DP, according to EN 50170 All with optical isolation.
Service-Interface	Ethernet: Modbus TCP
USB-Interface	Host for USB-Stick; max. 100mA
Supply voltage	24 V DC, +/-25 %, appr. 6W + Power of logic outputs
Data protection	EAROM, Semiconductor storage When using a Fieldbus interface please note: Permissible writing operations per parameter must not exceed 1 000 000.
Casing	Format, case: 96x96mm, acc. DIN 43700, Installation depth 122 mm

	Panel cut-out: Width=92 +0,5 mm x Height=90 +0,5 mm Material: Sheet steel and Makrolon UL 94-V1 Protection mode: IP 20 (DIN 40050), Front side: IP 50
Connectors	Service-Interface: Ethernet RJ45 USB-Interface: Type A Profibus: SUB-D 9 Others: spring-loaded push terminals, Protection mode IP 20 (DIN 40050), Insulation class C Cross-sections: Terminal groups: A, B, D, E, F, G, I, K, M, N, Q + C, H (continuous) = 1,5 mm <sup>2</sup> (for end sleeves with plastic collar 0,75mm <sup>2</sup> ) Terminal groups: C, H, (Relay), P = 2,5mm <sup>2</sup>
Real time clock	Backup battery: Lithium CR2032
Weight	Approx. 800g, depends on the version of the device
E-Bus	Bus system for connecting the R4020 to the extension module R4010, to expand the number of zones to 12 or 16 zones. Serial bus. The connecting cable must be shielded.
Permissible operating conditions	Operating: 0...50°C / 32...122°F Temperature: -30...70°C / -22...158°F Storage temperature: KWF DIN 40040; equivalent to annual average Climate class: max. 75% rel. humidity, no condensation
CE - mark	EN 61326-1:2013 / EN 61000-3-2:2006+A1:2009+A2:2009 EN 61000-3-3:1995+A1:2001+A2:2005 Electrical safety: EN 61010-1

Subject to technical improvements.